

Ul. Grzegorza z Sanoka 2 80 – 408 Gdańsk tel. (0-58) 341 42 45

# **OPERATION AND MAINTENANCE MANUAL**

Fire damper type mcr FID S/... c/P



Version FID C 25.06.03.25

FIRE VENTILATION SYSTEMS DEPARTMENT

## CONTENTS:

1. INTRODUCTION	4
2. THE SUBJECT OF THE MANUAL	4
3. DEVICE INTENDED USE	4
4. DEVICE DESIGN AND PRINCIPLE OF OPERATION	4
5. DEVICE LABELLING	7
6. DEVICE ASSEMBLY	7
6.1. INSPECTION BEFORE THE ASSEMBLY	7
6.2. FIXING HOLE	7
6.3. EMBEDDING	8
6.4. ELECTRICAL CONNECTIONS	14
7. TRANSPORT AND STORAGE CONDITIONS	20
8. MAINTENANCE AND SERVICE	20
9. WARRANTY CONDITIONS	21

## **CAUTION:**



Risk of injury from sharp edges, sharp corners and thin sheet metal parts. Be careful when working. Wear protective gloves, safety shoes and a helmet.

Danger of pinching your finger or damaging your hand when the damper partition is in operation. Be careful.

Danger of electric shock. Do not touch live components. Work related to electrical connections may only be performed by employees with appropriate qualifications and authorizations.

Before working on electrical equipment, disconnect the power supply

## Labelling used in the operation and maintenance manual



## NOTE

With the date of publication of the operation and maintenance manual, the previous versions are no longer valid.

The operation and maintenance manual does not concern the dampers manufactured before the date of its publication.

## CAUTION

The product should be stored and used in rooms where:

- there is no access to dust, gases, caustic vapors and other aggressive chemical vapors that can destroy the insulating elements and structural elements;
- the flaps are not affected by direct sunlight and UV radiation;
- the maximum relative humidity does not exceed 80% at the temperature of +20 °C;
- the ambient temperature is between 20 °C and + 40 °C;
- there are no vibrations.

In the event that harmful conditions exist or may occur in the place of use, additional measures must be taken to protect the product.

In the case of cut-off and transfer fire dampers, the device is equipped with a thermal release containing one-time temperature fuses. During normal operation, the above mentioned element should be protected against the affect of the permissible temperature Tmax (see the table below). When it is exceeded, the temperature fuses may operate, which is a normal operation and is not covered by the guarantee or warranty.

A thermal release for a damper equipped with an electric actuator:



Thermal fuse for temperature	72 °C	95 °C
Temperature fuse inside the duct	Tmax 40 °C	Tmax 60 °C
Outdoor temperature fuse	Tmax 40 °C	Tmax 40 °C

A thermal release for a damper equipped with KW1 or RST mechanism:



- Duct inside temperature fuse

Thermal fuse for temperature	72 °C	95 °C
Temperature fuse inside the duct	Tmax 40 °C	Tmax 60 °C



## 1. INTRODUCTION

The purpose of this operation and maintenance manual is to get the user acquainted with the intended use, design, the principle of operation, correct installation and operation of the product.

The manual also includes additional information about the operating conditions, maintenance and warranty conditions of the product.

#### 2. THE SUBJECT OF THE MANUAL

This manual concerns the entire group of single-plane fire dampers type mcr FID S/... c/P. Observing recommendations included in the manual ensures correct function of the device in terms of fire protection of rooms as well as safety of the system users.

#### 3. DEVICE INTENDED USE

#### Application

Single-plane fire dampers type mcr FID S/... c/P may be used:

fire dampers – mcr FID S/S c/P

smoke control dampers for fire ventilation systems - mcr FID S/V c/P

smoke control dampers for mixed fire ventilation systems – mcr FID S/M c/P

as transfer dampers – mcr FID S/T c/P

as relief dampers – mcr FID S/G c/P

The dampers may not work in systems exposed to dust, except for when they are included in a special, individually developed programme of service and technical inspections.

On request (non-standard execution), dampers can be made in a "version" of stainless/acid-resistant steel. This means that the elements made of galvanized steel, used in the standard version of the damper, will be replaced with stainless/acid-resistant steel. The remaining components of the damper (e.g. thermal releases, actuators, pins, blades, fire seals will be made of materials normally used for the production of the device).

#### Fire resistance

Damper type mcr FID S/S c/P have the fire resistance of:

		-					
	EI60S		/S	/V	/M	/T	EI120S
I	EI60		/S	/V	/M	/T	EI120
I	E60S		/S	/V	/M	/T	E120S
I	E60		/S	/V	/M	/T	E120
2			-				

/S	/V	/M	/T
/S	/V	/M	/T
/S	/V	/M	/T
/S	/V	/M	/T

depending on application, method and place of installation of the damper.

#### **Performance versions**

Dampers mcr FID S/... c/P may be performed as:

Rectangular dampers

Rectangular dampers with round connections

Round dampers

#### **Dimension type series**

Dampers mcr FID S/S c/P are performed in the following dimensions:

Width: between 100 and 1000 mm

Height: between 100 and 800 mm

Width: between 296 and 390 mm

Apart from the standard dimensions there is a possibility of performing dampers with intermediate dimensions. The maximum surface of dampers of type mcr FID S/S c/P equals:  $0.8 \text{ m}^2$ . The minimum surface of the dampers equals  $0.04 \text{ m}^2$ .

## 4. DEVICE DESIGN AND PRINCIPLE OF OPERATION

#### Design

The single-plane dampers mcr FID S/... c/P are made of an enclosure with a rectangular cross-section, a portable shut-off partition and a release and control mechanism activated manually or automatically after the thermal release is activated. The damper enclosure is made of a steel, galvanised steel sheet, or a stainless steel one. In the damper enclosure, on its circumference, the insulation perforation with the relevant width is performed. The shut-off partition of dampers is made of a non-flammable plate and is set in a sheet reinforcement profile. On the enclosure, in the place where the insulation is performed, there is a swelling gasket. The sealing at the partition circumference is effected by a rubber gasket installed on the partition. The enclosure is ended from both ends with flange connections.

## Action

The principle of action and behaviour of single-plane dampers mcr FID S/... c/P depends on the version of their application:

#### fire dampers – mcr FID S/S c/P

In normal operating position, the dampers are open. Closing the dampers (safety position) takes place:

- automatically, by activation of the thermoelectric release
  - manually, by pressing the control button at the thermoelectric release

remotely, by activation of an electric axial actuator with a return spring, as a result of removing its supply voltage

automatically, by activation of the thermal release and the actuation spring

#### smoke control dampers for fire ventilation systems – mcr FID S/V c/P

In normal operating position, the dampers are closed. Opening the dampers (safety position) takes place:

remotely, by activation of an electric axial actuator without a return spring, as a result of applying the supply voltage to the actuator in the right manner

remotely, by activation of the electromagnetic release and a spring as a result of applying the voltage

#### smoke control dampers for mixed fire ventilation systems – mcr FID S/V-M c/P

In normal operation dampers are closed or open, depending on the function carried out. Opening/closing the dampers (safety position) takes place:

remotely, by activation of the electrical axial actuator without a return spring in order to apply supply voltage to the actuator in the right manner

#### transfer fire dampers – mcr FID S/T c/P

In normal operating position, the dampers are open. Closing the dampers (safety position) takes place:

- automatically, by activation of the thermoelectric release
- manually, by pressing the control button at the thermoelectric release
- remotely, by activation of an electric axial actuator with a return spring, as a result of removing its supply voltage
- automatically, by activation of the thermal release and the actuation spring

#### relief fire dampers – mcr FID S/V c/P

In normal operating position, the dampers are closed or open. Opening/closing the dampers (safety position) takes place:

remotely, by activation of an electric axial actuator without a return spring, as a result of applying the supply voltage to the actuator in the right manner

It is possible to check the correctness of damper co-operation with an electrical actuator manually, for service purposes using a special hex wrench placed in the socket marked on the actuator, and rotated to set the damper partition in the relevant position. Wrench rotation should be done evenly, slowly and carefully. Too quick or too rapid rotation of the key may cause damage of the internal actuator mechanism, or damage of the drive transmission system.

In the integrated version it is possible to check the correctness of damper co-operation with a release and control manually, for service purposes by pressing a lever on the mechanism.

## NOTE

In any case it is forbidden to pull directly by the damper partition in order to open or close it. Such an action may cause damage of the devices' self-braking drive mechanism and is not covered by the warranty. It is recommended that the fire damper were opened and closed when the ventilation system is turned off. Release and control mechanisms

A release and control mechanism for mcr FID S/... c/P dampers can be:

#### An electrical motor





BE 230 BE 24 BLE 230 BLE 24 EXBF 230 EXBF 24 BF 24-TN-TL MF 24-T1 MLF 24-T1



## A spring mechanism:

RST
RST/KW1/24P
RST/KW1/230P

/S	/V	/M	/T
/S	/V	/M	/T
/S	/V	/M	/T



/S	/V	/M	/T
/S	/V	/M	/T
/S	/V	/M	/T

## Main dimensions



Gear	А	С	D	Е
BFN	157	30	75	57
BFL	138	30	75	53
BF 24TL-ST	198	10	75	65
EXBF	225	55	75	175
MF	198	30	75	70
MLF	114	30	75	62
* embedding border				

#### mcr FID S/... c/P fire damper with actuator



Gear	А	С	D	Е	
RST	50	30	75	70	
* embedding border					

mcr FID S/... c/P fire damper with RST



Gear	А	С	D	Е	
RST/KW1	130	30	75	80	
* embedding border					



## 5. DEVICE LABELLING



## 6. DEVICE ASSEMBLY

#### NOTE

During the assembly of dampers and the finishing works, take into account the possibility of access to the device later and the disassembly of release and control mechanism in order to carry out the possible service works and technical inspections.

The mcr FID S/... c/P dampers may be installed in the following partitions (walls or ceilings) in the wet system:

masonry walls - concrete with a thickness of at least 120 mm thick

masonry walls from bricks or blocks at least 120 mm thick

walls from panels at least 125 mm thick

ceilings of at least 150 mm thick\*

\* only for the maximum damper dimension BxH 800x400.

The mcr FID S/... c/P dampers may be installed in the following partitions (walls or ceilings) in the wet and dry system: masonry walls – concrete with a thickness of at least 125 mm thick

masonry walls from bricks or blocks at least 125 mm thick

walls from panels at least 125 mm thick

ceilings of at least 150 mm thick

Additionally, dampers can be installed:

outside walls

in dampers sets (multiple damper sets)

at close distances from each other, from the ceiling - vertical installation

at close distances from each other – horizontal installation

The mcr FID S/... c/P shut-off dampers may also be installed in partitions with a lower class of fire resistance. In case of such an installation, dampers have fire protection equal to the fire protection of the partition, maintaining the smoke tightness criteria. In the case of installing the damper in a specific type of wall with thickness lower than required, locally increase its thickness at the circumference of the installed damper, for instance by installing an additional panel or another construction element.

## 6.1. INSPECTION BEFORE THE ASSEMBLY

Each damper is inspected before packaging and transporting by the manufacturer. After unpacking at the recipient, inspect visually in terms of possible deformation of the casing or damper damage during transport.

## 6.2. FIXING HOLE

The recommended minimum dimensions of the hole which allows correct installation of a rectangular damper is:

- for dampers installed in a wet system, filling the gap between the partition and the damper: (B+90) x (H+90) mm.
- for dampers installed in a dry system, filling the gap between the wall and the damper: (B+100) x (H+100) mm



Preparation of the mounting hole for dampers install in the wet system.



Preparation of the mounting hole for dampers install in the dry system.

## 6.3. EMBEDDING / SETTING THE DAMPER

#### NOTE

Ensure that at each place of the damper circumference there is a 2.5 mm gap between the body and the partition. Fulfilling this comment is a condition of keeping the product warranty.



#### Securing the gap size between the damper body and the partition.



#### Protecting the damper against buckling.

Correctness of the mcr FID S/... c/P damper is maintained when the partition rotation axis is horizontal or vertical. The release and control mechanism may be located on the right or on the left hand side of the damper at any direction of air flow.

Before embedding/setting, place the damper axially in the partition (wall or ceiling which separates fire zones) in the previously prepared hole. Then, level out and secure the device. After these actions, manually start the damper partition, checking whether it rotates correctly (does not collide with the enclosure elements etc.). Close the damper partition. Carefully fill the gap between the damper casing and the wall with the right mortar that ensures wall and damper fire resistance, taking particular attention so that it does not get on the acting elements (release and control mechanism, partition, gaskets, limits). To ensure it, it is mandatory to secure the damper with film, or any other cover until the masonry and finishing works are concluded. The damper must remain closed until the mortar binds. After the mortar binds, remove supports, open and close the damper in order to check the correctness of its operation. When the damper is installed in a dry system, the space between the damper casing and the building partition should be tightly filled with mineral wool with A1 non-flammability class confirmed by a certificate, and the density and thickness ensuring fire resistance not lower than the resistance of the building partition in which the damper is installed. The filled space and the wall according to the drawings below should be additionally sealed with a suitable mortar or paint with confirmed fire resistance required for the wall.

In order to ensure the fire resistance of the fire separation element, it is mandatory to observe the border of embedding - the damper rotation axis must not be outside the wall.

Connecting the embedded damper to the ventilation duct has to be made coaxially. During the damper installation, the damage to the damper body should be prevented, particularly its strains. The damper may not be a "load bearing element" of the duct or the ventilation system on which it is installed. Drilling through the damper enclosure, driving screws, bolts or other elements passing through the enclosure to the inside of the damper is unacceptable. After connecting the ventilation duct, check the correctness of damper operation again.

During the installation of a mcr FID S/... c/P damper, pay particular attention so that the thermal release (fuse element) do not get damaged, do not expose it to high temperature (fire, welders, soldering irons) that cause its activation (it is a single use element and is not subject to warranty replacement). Do not expose swelling gaskets installed in the damper enclosure to high temperature. Gasket swelling makes it impossible to close the damper. After finishing the installation, carefully clean the damper and make sure that there is no debris which could influence the correctness of operation.

#### NOTE

It is crucial to observe the device embedding border, so that the release and control mechanism is outside the separation wall and allows easy access.



#### Installation of the mcr FID S/... c/P damper in a panel wall in wet and dry system.

Recommended protection of the installation passage in a dry system based on wool of min. 100 kg / m3 with nonflammability class A1 and securing the contact point of the damper with the wall and wall with fire protection intumescent paint mcr Polylac Elastic thickness 1mm, according to the picture above. The manufacturer allows the use of other materials with parameters not worse than the recommended solution and has the appropriate approval documents confirming the appropriate class of fire resistance.



#### Installation of the FID S/... c/P damper in a concrete block or full brick walls in wet system.

The recommended protection of the installation passage in the wet system is based on cement or gypsum mortar. The manufacturer allows the use of other materials with parameters not worse than the recommended solution and has the appropriate approval documents confirming the appropriate class of fire resistance.



Installation of the FID S/... c/P damper in a concrete block or full brick walls in dry system.

Recommended protection of the installation passage in a dry system based on wool of min. 100 kg / m3 with nonflammability class A1 and securing the contact point of the damper with the wall and wall with fire protection intumescent paint mcr Polylac Elastic thickness 1mm, according to the picture above. The manufacturer allows the use of other materials with parameters not worse than the recommended solution and has the appropriate approval documents confirming the appropriate class of fire resistance.



- 1. Ventilation duct
- 2. Sheet-metal screw ST4.2x16
- 3. Damper mcr FID S/... c/P
- 4. Mortar
- 5. Ceiling
- X Ceiling thickness

#### Installation of a FID S/... c/P damper in a ceiling.

The recommended protection of the installation passage in the wet system is based on cement or gypsum mortar. The manufacturer allows the use of other materials with parameters not worse than the recommended solution and has the appropriate approval documents confirming the appropriate class of fire resistance.



#### Installation of the mcr FID S/... c/P fire damper as a multiple damper set (a set of 4).

Other configurations of the mcr FID S /... c/P dampers modules can be made, consisting of two or more dampers, while maintaining the minimum distances between the dampers according to the drawing above.

The recommended protection of the installation passage in the wet system is based on cement or gypsum mortar. The manufacturer allows the use of other materials with parameters not worse than the recommended solution and has the appropriate approval documents confirming the appropriate class of fire resistance.



- 1. Damper mcr FID S/... c/P
- 2. Mortar
- 3. Concrete block or full brick walls or panel wall
- 4. Ceiling

Minimum installation distances of the damper from the ceiling, according to the drawings. A band around the perimeter of the flap is required, made of non-flammable board (e.g. plasterboard) with a thickness of at least 10 mm for flexible walls and 15 mm for rigid walls.

#### Installation of the mcr FID S/... c/P fire damper in the wall close to the ceiling

The recommended protection of the installation passage in the wet system is based on cement or gypsum mortar. Recommended protection of the installation passage in a dry system based on wool of min. 100 kg / m3 with non-flammability class A1 and securing the contact point of the damper with the wall and wall with fire protection intumescent paint mcr Polylac Elastic thickness 1mm, according to the picture above. The manufacturer allows the use of other materials with parameters not worse than the recommended solution and has the appropriate approval documents confirming the appropriate class of fire resistance.





- 1. Damper mcr FID S/... c/P
- 2. Mortar
- 3. Concrete block or full brick walls or panel wall

The damper can be installed in close proximity to the damper (damper next to the damper, damper above the damper, damper diagonally to damper) provided that the minimum installation distance is maintained, as shown in the drawings. Bands required around the perimeter of the flaps are made of non-flammable board (e.g. plasterboard) with a thickness of at least 10 mm for flexible walls and 15 mm for rigid walls.

#### Installation of the mcr FID S/... c/P fire damper in the wall in close proximity to each other

The recommended protection of the installation passage in the wet system is based on cement or gypsum mortar. Recommended protection of the installation passage in a dry system based on wool of min. 100 kg / m3 with non-flammability class A1 and securing the contact point of the damper with the wall and wall with fire protection intumescent paint mcr Polylac Elastic thickness 1mm, according to the picture above. The manufacturer allows the use of other materials with parameters not worse than the recommended solution and has the appropriate approval documents confirming the appropriate class of fire resistance.

## **6.4. ELECTRICAL CONNECTIONS**

After correct embedding of the damper, if it has control elements or other elements that require connecting the electrical installation, connect the lines of this installation to the damper. Below we can see the connection diagrams and the basic electrical data of the release and control mechanisms supplied with the mcr FID S/... c/P dampers.

## 6.4.1. Electric actuators – electrical specification

Actuator type	Location of the damper isolation partition
<ul> <li>Belimo BFL series</li> <li>Belimo BFN series</li> <li>Belimo BF series</li> <li>Mercor MF series</li> <li>Mercor MLF series</li> </ul>	Open isolation partition – actuator indication: 90 Closed isolation partition – actuator indication: 0
- Belimo serii BE - Belimo serii BLE - Belimo serii BEE - Belimo serii BEN	Open isolation partition – actuator indication: 0 Closed isolation partition – actuator indication: 90

Power supply         AC 24V 50/60Hz DC 24V         AC 220-240V 50/60 Hz DC 24 V         AC 24V 50/60Hz DC 24 V         AC 220-240V 50/60 Hz DC 24 V           Power demand:         7 W $8.5$ W $7.2$ W $4.2$ W           - for spring holding         2 W         3 W $2.5$ W $2.5$ W           Sizing (apparent power)         10 VA         11 VA         8 VA         8 VA           Appliance class         III         II         III         III         II           Ingress protection rating         IP 54         IP 54         IP 54         IP 54           Auxiliary circuit breaker: $6(3) A, 250V$ $3A, 250V \sim 3(1,5)A AC 250V$ $3(1,5)A AC 250V$ $3(1,5)A AC 250V$ - activation position [degrees]         5°, 80°         5°, 80°         5°, 80°         5°, 80°         5°, 80°           - spring         12 Nm         12 Nm         5 Nm         5 Nm         5 Nm           - spring         12 Nm         12 Nm         5 Nm         5 Nm         5 Nm           - spring         2 X0,75 mm <sup>2</sup> 2 X0,75 mm <sup>2</sup> 2 X0,75 mm <sup>2</sup> 2 X0,75 mm <sup>2</sup> 6 X0,75 mm <sup>2</sup> - auxiliary circuit breaker         6 X0,75 mm <sup>2</sup> 6 X0,75 mm <sup>2</sup> 6 X0,75 mm <sup>2</sup>	Technical specifications	BF 24, BF24-T, BF24-TN	BF230, BF230-T, BF230-TN	MLF 24, MLF24 T1	MLF230, MLF230 T1
Power demand: - for spring tensioning7 W $8,5$ W $7.2$ W $4.2$ W- for spring holding2 W3 W $2,5$ W $2.5$ WSizing (apparent power)10 VA11 VA $8$ VA $8$ VAAppliance classIIIIIIIIIIIIngress protection ratingIP 54IP 54IP 54Ingress protection ratingIP 54IP 54IP 54Auxiliary circuit breaker: $6(3)$ A, 250V $3$ A, 250V~ $3(1,5)$ A AC 250V- activation position $5^{\circ}$ , $80^{\circ}$ $5^{\circ}$ , $80^{\circ}$ $5^{\circ}$ , $80^{\circ}$ Torque: - motor18 Nm18 Nm $5$ Nm $5$ Nm- motor (L = 0.9 m) $2x0,75$ mm² $2x0,75$ mm² $2x0,75$ mm²- auxiliary circuit breaker $6x0,75$ mm² $6x0,75$ mm² $6x0,75$ mm²- motor (L = 0.9 m) $2x0,75$ mm² $2x0,75$ mm² $6x0,75$ mm2- motor (L = 0.9 m) $2x0,75$ mm² $120$ s $75-80$ s- return spring16 s $16$ s $20$ s $20$ s- return spring16 s $16$ s $20$ s $20$ s- return spring16 s $16$ s $20$ s $20$ s- return spring $16$ s $16$ s $20$ s $20$ s- return spring $16$ s $16$ s $20$ s $20$ s- return spring $16$ s $16$ s $20$ s $20$ s- return spring $16$ s $16$ s $20$ s $20$ s- return spring $16$ s $16$ s $20$ s $-30$ +50°C- rotor <td>Power supply</td> <td>AC 24V 50/60Hz DC 24V</td> <td>AC 220-240V 50/60 Hz</td> <td>AC 24V 50/60Hz DC 24 V</td> <td>AC 220-240V 50/60 Hz</td>	Power supply	AC 24V 50/60Hz DC 24V	AC 220-240V 50/60 Hz	AC 24V 50/60Hz DC 24 V	AC 220-240V 50/60 Hz
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	Power demand:				
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	- for spring tensioning	7 W	8,5 W	7.2 W	4.2 W
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	- for spring holding	2 W	3 W	2,5 W	2.5 W
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	Sizing (apparent power)	10 VA	11 VA	8 VA	8 VA
Ingress protection ratingIP 54IP 54IP 54IP 54IP 54Auxiliary circuit breaker: $2xSPDT$ $2xSPDT$ $2xSPDT$ $2xSPDT$ $2xSPDT$ - activation position $5^{\circ}, 80^{\circ}$ $5^{\circ}, 80^{\circ}$ $5^{\circ}, 80^{\circ}$ $5^{\circ}, 80^{\circ}$ $5^{\circ}, 80^{\circ}$ Idegrees] $5^{\circ}, 80^{\circ}$ $5^{\circ}, 80^{\circ}$ $5^{\circ}, 80^{\circ}$ $5^{\circ}, 80^{\circ}$ $5^{\circ}, 80^{\circ}$ Torque: motor18 Nm18 Nm5 Nm5 Nm- spring12 Nm12 Nm5 Nm5 NmCable connection: motor (L = 0.9 m) $2x0,75 mm^2$ $2x0,75 mm^2$ $2x0,75 mm2$ - auxiliary circuit breaker $6x0,75 mm^2$ $6x0,75 mm^2$ $6x0,75 mm2$ - motor (L = 0.9 m) $120 \text{ s}$ $120 \text{ s}$ $75-80 \text{ s}$ $75-80 \text{ s}$ - motor120 s $120 \text{ s}$ $75-80 \text{ s}$ $75-80 \text{ s}$ $75-80 \text{ s}$ - motor $120 \text{ s}$ $16 \text{ s}$ $20 \text{ s}$ $20 \text{ s}$ $20 \text{ s}$ Operating temperature range $-30 \dots + 50^{\circ} \text{C}$ Sound pressure level: - motormax 45 dB (A)max 45 dB (A)max 45 dB (A)max 45 dB (A)- motor $x63 dB(A)$ $xe 63 dB(A)$ $xe 63 dB(A)$ $xe 63 dB(A)$	Appliance class		I		II
Auxiliary circuit breaker: $2xSPDT$ 6 (3) A, 250V $2xSPDT$ 3 A, 250V~ $2xSPDT$ 3 (1,5)A AC 250V $2xSPDT$ 3 (1,5)A AC 250V- activation position [degrees] $5^{\circ}$ , 80° $5^{\circ}$ , 80° $5^{\circ}$ , 80° $5^{\circ}$ , 80° $5^{\circ}$ , 80°Torque: - motor18 Nm18 Nm5 Nm5 Nm- spring12 Nm12 Nm5 Nm5 NmCable connection: - motor (L = 0.9 m)2x0,75 mm²2x0,75 mm²2x0,75 mm²- auxiliary circuit breaker6x0,75 mm²6x0,75 mm²6x0,75 mm²Movement time: (0-90°) - motor120 s120 s120 s75-80s- return spring16 s16 s20s20sOperating temperature range- 30+50°C- 30+50°C- 30+50°CSound pressure level: 	Ingress protection rating	IP 54	IP 54	IP 54	IP 54
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	Auxiliary circuit breaker:	2xSPDT 6 (3) A, 250V	2xSPDT 3 A, 250V~	2xSPDT 3(1,5)A AC 250V	2xSPDT 3(1,5)A AC 250V
Torque:         18 Nm         18 Nm         5 Nm         5 Nm           - motor         12 Nm         12 Nm         5 Nm         5 Nm           - spring         12 Nm         12 Nm         5 Nm         5 Nm           Cable connection:         -         2x0,75 mm²         2x0,75 mm²         2x0,75 mm²           - motor (L = 0.9 m)         2x0,75 mm²         6x0,75 mm²         6x0,75 mm²         6x0,75 mm²           - auxiliary circuit breaker         6x0,75 mm²         6x0,75 mm²         6x0,75 mm²         6x0,75 mm²           - motor         120 s         120 s         120 s         75-80s         75-80s           - return spring         16 s         16 s         20s         20s         20s           Operating temperature range         - 30+50°C         - 30+50°C         - 30+50°C         - 30+50°C         - 30+50°C           Sound pressure level:         -         -         -         -         -         -         -         -         -         -         30+50°C         -         -         -         -         30+50°C         -         -         30+50°C         -         -         -         30+50°C         -         -         30+50°C	<ul> <li>activation position</li> <li>[degrees]</li> </ul>	5°, 80°	5°, 80°	5°, 80°	5°, 80°
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	Torque:				
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	- motor	18 Nm	18 Nm	5 Nm	5 Nm
Cable connection: $2x0,75 \text{ mm}^2$ $6x0,75 \text{ mm}^2$ $75-80s$ $75-80s$ $75-80s$ $20s$	- spring	12 Nm	12 Nm	5 Nm	5 Nm
- motor (L = $0.9 \text{ m}$ ) $2x0,75 \text{ mm}^2$ $6x0,75 \text{ mm}^2$ $75-80s$ $75-80s$ $75-80s$ $20s$ $30 \dots +50^{\circ}$ C $-30 \dots +50^{\circ}$ C $-30 \dots +50^{\circ}$ C $-30 \dots +50^{\circ}$ C $-30 \dots +50^{\circ}$ C $30 \dots$	Cable connection:				
- auxiliary circuit breaker         6x0, 75 mm²         75-80s         75-	- motor (L = $0.9 \text{ m}$ )	2x0,75 mm <sup>2</sup>	2x0,75 mm <sup>2</sup>	2x0,75 mm2	2x0,75 mm2
Movement time:         (0-90°)         120 s         120 s         120 s         75-80s         75-80s         75-80s         20s         20s <t< td=""><td>- auxiliary circuit breaker</td><td>6x0,75 mm<sup>2</sup></td><td>6x0,75 mm<sup>2</sup></td><td>6x0,75 mm2</td><td>6x0,75 mm2</td></t<>	- auxiliary circuit breaker	6x0,75 mm <sup>2</sup>	6x0,75 mm <sup>2</sup>	6x0,75 mm2	6x0,75 mm2
- motor         120 s         120 s         120 s         75-80s         75-80s           - return spring         16 s         16 s         20s         20s           Operating temperature range         - 30+50°C         - 30+50°C         - 30+50°C         - 30+50°C           Sound pressure level:         - motor         max 45 dB (A)         max 45 dB (A)         max 45 dB (A)	Movement time: (0-90°)	100	400	75.00	75.00
- return spring         16 s         20s         20s           Operating temperature range         - 30+50°C         - 30+50°C         - 30+50°C         - 30+50°C           Sound pressure level:         -         -         -         -         -         -         -         -         30+50°C         -         -         30+50°C         -         -         30+50°C         -         30	- motor	120 s	120 s	75-80s	75-80s
Operating temperature range         - 30+50°C         - 30+50°C         - 30+50°C           Sound pressure level:         -         -         -         -         -         30+50°C         -         -         30+50°C         - <td>- return spring</td> <td>16 S</td> <td>16 S</td> <td>20\$</td> <td>205</td>	- return spring	16 S	16 S	20\$	205
range     range       Sound pressure level:     - motor       - motor     max 45 dB (A)       - spring     - e 63 dB (A)	Operating temperature	- 30+50°C	- 30+50°C	- 30+50°C	- 30+50°C
- motor max 45 dB (A)					
- motor max 45 db (A) $(A)$	sound pressure level:	max 4E dP(A)	max 45 dP (A)	max 45 dP (A)	max 45 dP (A)
	- spring	~ 63 dB (A)	$\sim 63 \text{ dB} (A)$	max 45 ub (A)	max 40 ub (A)

Technical specifications - Actuators	BE24, BE24-ST	BE230	BLE24, BLE24-ST	BLE230
Power supply	AC 24V 50/60Hz DC 24 V	AC 220-240V 50/60 Hz	AC 24V 50/60Hz DC 24V	AC 220-240V 50/60 Hz
Power demand: - for spring tensioning	12 W	8 W	7.5 W	5 W
Sizing (apparent power)	18 VA	15 VA	9 VA	12 VA
Appliance class	111	II		
Ingress protection rating	IP 54	IP 54	IP 54	IP 54
Auxiliary circuit breaker:	2xSPDT 6(3) A, 250V	2xSPDT 6(3) A, 250V	2xSPDT 3A, AC 250V	2xSPDT 3A, AC 250V
- activation position [degrees]	3°, 87°	3°, 87°	3°, 87°	3°, 87°
Torque: - motor	40 Nm	40 Nm	15 Nm	15 Nm
- locking Cable connection:	50 MM	50 MM	20 MM	20 NM
- motor (L = $0.9 \text{ m}$ )	3x0,75 mm2	3x0,75 mm2	3x0,75 mm2	3x0,75 mm2
- auxiliary circuit breaker	6x0,75 mm2	6x0,75 mm2	6x0,75 mm2	6x0,75 mm2

**MERCOR** – The company reserves the right to modify and change the document.

Movement time: (0-90°)	605	60 a	30 0	30 c
- motor	805	60 S	30 \$	30 \$
Operating temperature range	- 30+50°C	- 30+50°C	- 30+50°C	- 30+50°C
Sound pressure level:				
- motor	max 62 dB (A)			

Technical specifications - Actuators	BEE24, BEE24-ST	BEE230	BEN24, BEN24-ST	BEN230
Power supply	AC 24V 50/60Hz DC 24 V	AC 220-240V 50/60 Hz	AC 24V 50/60Hz DC 24V	AC 220-240V 50/60 Hz
Power demand:				
<ul> <li>for spring tensioning</li> </ul>	2,5 W	3,5 W	3 W	4 W
- for spring holding	0,1W	0,4 W	0,1 W	0,4 W
Sizing (apparent power)	5 VA	6 VA	6 VA	7 VA
Appliance class	III	II	111	I
Ingress protection rating	IP 54	IP 54	IP 54	IP 54
Auxiliant aircuit brookers	2xSPDT	2xSPDT	2xSPDT	2xSPDT
Auxiliary circuit breaker.	3A AC 250V	3A AC 250V	3A, AC 250V	3A, AC 250V
- activation position [degrees]	5°, 80°	5°, 80°	5°, 80°	5°, 80°
Torque:				
- motor	25 Nm	25 Nm	15 Nm	15 Nm
Cable connection:				
- motor (L = 0.9 m)	3x0,75 mm2	3x0,75 mm2	3x0,75 mm2	3x0,75 mm2
- auxiliary circuit breaker	6x0,75 mm2	6x0,75 mm2	6x0,75 mm2	6x0,75 mm2
Movement time: (0-90°)	600	60 a	20 a	20 a
- motor	605	60 S	30 \$	30 \$
Operating temperature range	- 30+55°C	- 30+55°C	- 30+55°C	- 30+55°C
Sound pressure level:				
- motor	max 58 dB (A)	max 58 dB (A)	max 58 dB (A)	max 58 dB (A)

Technical data – actuators	BFL24, BFL24-T	BFL230, BFL230-T	BFN24, BFN24-T	BFN230, BFN230-T
Power supply	AC 24 V 50/60 Hz DC 24 V	AC 220–240 V 50/60 Hz	AC 24 V 50/60 Hz DC 24 V	AC 220-240V 50/60 Hz
Power demand:				
<ul> <li>when putting the spring under</li> </ul>				
tension	2.5 W	3,5 W	4 W	5 W
<ul> <li>when in standby</li> </ul>	0.7 W	1.1 W	1.4 W	2.1 W
Apparent power	4 VA	6.5 VA	6 VA	10 VA
Protection class				<u> </u>
IP rating	IP 54	IP 54	IP 54	IP 54
	2 x PDT	2 x PDT	2 x SPDT	2 x SPDT
auxiliary switch:	3(0.5) A AC 250V	3(0.5) A AC 250V	3(0.5) A, 250 V	3(0.5) A, 250 V
- activation point [degrees]	5°, 80°	5°, 80°	5°, 80°	5°, 80°
Torque:				
- motor	4 Nm	4 Nm	9 Nm	9 Nm
- spring	3 Nm	3 Nm	7 Nm	7 Nm
Wire connection:				
– motor (length: 0.9 m)	2 x 0.75 mm <sup>2</sup>	2 x 0.75 mm <sup>2</sup>	2 x 0.75 mm <sup>2</sup>	2 x 0.75 mm <sup>2</sup>
<ul> <li>auxiliary switch</li> </ul>	6 x 0.75 mm <sup>2</sup>	6 x 0.75 mm <sup>2</sup>	6 x 0.75 mm <sup>2</sup>	6 x 0.75 mm <sup>2</sup>
Movement time (0–90°):				
- motor	60 s	60	60 s	60 s
- return spring	≈ 20 s	≈ 20 s	≈ 20 s	≈ 20 s
Working temperature range	−30+55°C	−30+55°C	−30+55°C	−30+55°C
Sound pressure level:				
- motor	max 43 dB (A)	max 43 dB (A)	max 55 dB (A)	max 55 dB (A)
- spring	~ 62 dB (A)	~ 62 dB (A)	~ 67 dB (A)	~ 67 dB (A)



Connection diagram for the BF24-Tand BF230-T actuators



Connection diagram for the BFL24-T, BFL230-T, BFN24-T, BFN230-T, BF24-TN and BF230-TN actuators



#### Connection diagram for the BE24, BLE24, BE230 and BLE230 actuators



#### Connection diagram for the BEE24, BEN24, BEE230 and BEN230 actuators



#### Connection diagram for the MLF24 T1 and MLF230 T1 actuators

**Note:** MLF/MF actuator cables are not marked with symbols. It should be connected based on the colors of the wires.

#### MLF230-T1 Actuator

S1 - Yellow	S4 - Violet
S2 - Blue	S5 - Gray
S3 - Green	S6 - White

#### MLF24-T1 Actuator

S1 – Yellow	S4 - Violet
S2 - Blue	S5 - Gray
S3 - Green	S6 - White

#### Note:

Controlling the operation of BE and BLE actuators requires connecting them to an electrical wiring system using three-wire cables. The change of rotation direction is effected by applying supply voltage to terminal 2 or 3, depending on the desired direction of rotation.

The position of limit switches for all actuator types applies to a potential free position.

For proper operation of a device equipped with electrical actuators, it is recommended that the rated voltage housed tolerance of 24V±10% or 230V±10%. Power supply devices other than listed above may cause malfunction and will not be covered by the warranty conditions.

## 6.4.2. EXBF actuators

Technical specification	EXBF 24	EXBF 230			
Zone	1, 2, 21, 22				
ATEX class	ll 2 GD E	Ex d IIC T6			
Power supply	24 V AC ±20% 50/60 Hz/24 VDC-10/+20%	230 V AC ±14% 50/60 Hz			
Power demand:					
<ul> <li>when putting the spring</li> </ul>	7 W				
under tension		8 W			
<ul> <li>when in standby</li> </ul>	2 W	3 W			
Apparent power	10 VA	12.5 VA			
IP rating	IP 66	IP 66			
Auxiliary switch:	2 x SPDT 6A (3) max. 250 V AC	2 x SPDT 6A (3) max. 250 V AC			
<ul> <li>activation point</li> </ul>	5°, 80°	5°, 80°			
Torque:					
– motor	18 Nm	18 Nm			
– spring	12 Nm	12 Nm			
Movement time: (90°C)					
– motor	150 s	150 s			
<ul> <li>return spring</li> </ul>	≈20 s	≈20 s			
Ambient temperature	-20+50°C	-20+50°C			



# Wiring diagram for EXBF actuators Caution:

For proper operation of a device equipped with electrical actuators, it is recommended that the rated voltage housed tolerance of 24V±10% or 230V±10%. Power supply devices other than listed above may cause malfunction and will not be covered by the warranty conditions.

## 6.4.3. RST/KW1 release and control mechanism

In the RST/KW1/S manufacturing version, the limit switches are installed on the mechanism itself. Electrical connection is carried out by connecting the wires (marked accordingly) to the electrical wiring system. The fusible release link is installed on the mechanism itself. The dampers with the RST/KW1/230I, RST/KW1/230P mechanisms, are supplied with the RST/KW1/24... triggering and control mechanism, together with the 230/24V transformer module type MP230/24. For the trigger and control mechanism of the "impulse" type damper, adequate power must be provided to ensure that the control signal is supplied to the device in the event of fire.

	RST/KW1/S	RST/KW1/24I	RST/KW1/24P	RST/KW1/24I +MP230/24	RST/KW1/24I	
Supply voltage	Х	24V–48V DC	24V-48V DC	230V AC	230V AC	
Power consumption	Х	3.5 W	1.6 W	4.5 W	2.5 W	
Holding force	Х	12 daN	12 daN	12 daN	12 daN	
Thermal release actuation temperature		72°C ±2°C				
WK1d or WK2d limit switch	NO/NC (changeover switch) 5A, 230V AC					
Limit switches actuation	3°, 87°, ±2° tolerance					
Limit switches working temperature	-25+85°C					

Electrical connection	х	<ul> <li>release: 0.6 m cable, 2 x 0.5 mm<sup>2</sup></li> <li>limit switch: 0.6 m cable, 6 x 0.5 mm<sup>2</sup></li> </ul>			
Rotation angle	92°				
Movement time	$\leq 2 \text{ s (spring)}$				
Rotation direction	left				
Mechanism weight	1.2 kg	1.4 kg	1.4 kg	1.5 kg	1.5 kg

KW1 mechanism power supply	WK1 limit switch	WK2 limit switch	
Wire no. 1–2	Wire no. 3–4, NC type (normally closed) Green / geay	Wire no. 6–7, NO type (normally open) Brown / pink	
	Wire no. 4–5, NO type (normally open) Gray / blue	Wire no. 7–8, NC type (normally closed) Pink / vellow	



## 24 V=

#### Connection diagram for transformer module type MP230/24

230 V~

**Note! The mechanism limit switches position has been provided for the safety position of the fire damper.** For proper operation of a device equipped with electrical actuators, it is recommended that the rated voltage housed tolerance of 24V±2% or 230V±2%. Power supply devices other than listed above may cause malfunction and will not be covered by the warranty conditions.

## 6.4.4. Release and control mechanism RST

In the RST version, the limit switches are installed inside the damper enclosure as independent subassemblies. The fuse release can be found on the damper partition. The drive spring is installed on the damper partition. In order to install the fuse release in the RST version:

- Set the damper partition in the open position using a hex wrench placed in the socket on the mechanism, and rotated to set the damper partition in the relevant position.
- We put the fuse cells on hooks attached to the damper body and to the partition.
- With the nut we pull and lock the hook by tightening so that the flap baffle is completely open



The mounting and fixing locations of the fuse element depend on the dimension H (flap height): A - For H from 200 to 235 – the fuse is fixed between the partition and the flap body B - For H from 236 to 399 – the fuse is mounted between the baffle lever and the flap body

C - For H from 400 to 800 – the fuse is mounted between the baffle lever and the angle bracket mounted on the flap body.

Independent damper limit switches - for the RST variant

WK1 – a single switch – signalling the state of closing the damper partition.

WK2 – a set of two switches – signalling the state of closing and opening the damper partition.

#### Switch technical data

Limit switch WK1 and WK2	1xNO/1xNC SPDT (switching contact) 5A, 230V AC
Temperature of operation of limit switches	-25+85ºC
Cabinet	Plastic



#### Warning

The moment the partition closes, the switch signalling the damper closing is controlled (contact 2-3 is closed).

С

Electric connection diagram of limiting switches WK1 and WK2

## 7. TRANSPORT AND STORAGE CONDITIONS

Fire dampers are packaged in cardboard boxes or placed on pallets. Dampers are protected against damage by film or another covering material. Damper transport may take place using any means of transport, provided they are protected against weather factors. Dampers placed on means of transport should be secured against shifting of position during transport. Before installing dampers, control each of them visually. Do not move the damper by holding by the connection cable or put a device on a release and control mechanism. Do not hit or drop the damper. When moving and installing, support the damper on the sides or edges of the body.

Dampers should be stored in closed rooms that provide protection against external weather conditions. In the case dampers are stored on the ground, place them on protection pads in order to protect them against damage. Storage should take place in rooms where:

• there is no access to dust, gases, caustic vapors and other aggressive chemical vapors that can destroy insulating elements and structural elements;

- · the dampers are not affected by direct sunlight and UV radiation;
- maximum relative humidity does not exceed 80% at the temperature of + 20 °C;
- the ambient temperature is between 20 °C and + 40 °C;
- there are no vibrations.

## 8. MAINTENANCE AND SERVICE

MERCOR devices should undergo periodical technical inspections and maintenance actions, no less frequent than 12 months during the entire operation period, that is during the warranty period and after it. Inspections and maintenance should be carried out by the manufacturer or by companies that have authorisation for servicing of MERCOR devices.

The obligation to carry our regular service inspections of fire protection devices results from the Art. 3(3) of the Regulation by the Minister of Internal Affairs and Administration of 7 June 2010 on fire protection of buildings, other civil structures and areas (Journal of Laws of 2010 No. 109, item 719).

It is recommended to execute, between inspections, the following:

- Inspections of the condition of electrical conditions, taking the mechanical damage particularly into account.
- Inspections of the condition of the supply voltage for the devices, which allowed the following tolerances:
  - 24V±10% for electric actuators
  - > 24V±2% for electromagnetic release mechanism
  - > 230V ±10% for electric actuators
  - > 230V±2% for electromagnetic release mechanism
- Inspections of the condition of the devices' body, taking the mechanical damage particularly into account.
- Checking whether there are no obstacles which could influence correct operation of the devices.

To enable the performance of actions included in the range of service inspections, as well as service and warranty actions such as visual inspections or repairs it is mandatory that the user provides the physical access to the devices, e.g. by disassembly of the thermal insulation, disassembly of suspended ceilings, disassembly of other systems if they prevent free access to the device etc.

In the case of devices installed in ducts, it is recommended to carry out the revisions, e.g. mcr KRW type. If devices are installed on the roof, ensure the possibility to enter the roof (ladder or lift).

In the matters related with technical inspections, maintenance and the device service, contact the representatives of the Service Department of MERCOR serwis@mercor.com.pl, tel. 058/ 341 42 45 internal 170 or fax 058/ 341 39 85 from 8 AM to 8 PM (Mon - Fri).

## 9. WARRANTY CONDITIONS

- 1. MERCOR grants 12 months of warranty for the equipment quality from the date of purchase, unless the sales contract states otherwise.
- 2. Submit each warranty claim to MERCOR in 7 days from the date of discovery of a warranty eligible defect
- 3. Submit warranty claims by calling at: tel. +48 58 341 42 45, by fax: +48 58 341 39 85, by e-mail: reklamacje@mercor.com.pl or by traditional mail: MERCOR, ul. Grzegorza z Sanoka 2, 80-408 Gdańsk, Poland.
- 4. If physical defects of equipment are found during the warranty period, MERCOR warrants and represents to remove them in shortest possible time from serving the written warranty claim with the proof of purchase or sales contract, subject to Item 10.
- 5. MERCOR has the right to extend the time of repair if the defect removal is complicated or requires purchase of custom components or spare parts.
- 6. The warranty liability only covers all defects arising from causes present in the equipment at the date of sale.
- 7. Defects caused by improper operation or otherwise as listed in Item 10 herein, the buyer / warranty beneficiary will be charged with the costs of their removal.
- 8. Condition for rectifying defects is that the applicant makes the site/localisation where devices are installed available, in particular, ensuring: the lift in the case of devices mounted at a height above 3m, free access to the rooms where the devices were installed and necessary revisions, dismantling thermal insulation, disassembling suspended ceilings, disassembling other installations, if they prevent free access to the device.
- 9. If the device can not be repaired at the place of its installation, MERCOR reserves the necessity of its disassembly, possible delivery to the address indicated by MERCOR and re-assembly. The cost of this operation lies with the buyer / holder of the guarantee.
- 10. The warranty does not cover:
  - Any damage or failure of the equipment caused by improper operation, tampering, failure to conduct periodic technical inspection and/or maintenance established in the Operating and Maintenance Manual, section "SERVICING AND MAINTENANCE".

- Any damage beyond reasonable control of MERCOR, and specifically: caused by force majeure, such as torrential rainfall, flooding, hurricanes, inundation, lightning strike, power grid overvoltage, explosion, hail, collision with aircraft, fire, avalanche, landslide and indirect damage due to those causes. Torrential rainfall is understood as any rainfall with the effectiveness factor of 4 or higher in accordance with the definition of the Polish Institute of Meteorology and Water Management - National Research Institute (IMGW-PIB). If the effectiveness factor value specified in the preceding sentence cannot be reasonably established, the actual condition and extent of damage shall be considered at the site of their origin as the action of torrential rain. Hurricane is understood as any wind with a minimum speed of 17.5 m/s (and damage shall be recognised as caused by hurricanes if the effects of such weather phenomenon has been found in the direct vicinity of the damaged property).
- Damage due to failure to immediately report any defect found.
- Deterioration in the quality of coatings due to natural weathering/ageing.
- Defects caused by abrasive or aggressive cleaning agents.
- Damage caused by aggressive external influence, specifically chemical or biological in nature, or when the origin of which is related to the production processing or activity carried out within the facility protected by the equipment or in its direct vicinity. If the devices are used in the above-mentioned places, they should be additionally and independently protected against factors prevailing in the place of their work.
- Wearing parts and consumables (e.g. gaskets/seals), unless they have defects of workmanship and/or material.
- Damage caused by improper transport, handling, unloading and/or storage of the equipment.
- Damage caused by installation of the equipment in violation of this Operating and Maintenance Manual and/or good construction practice.
- The equipment and/or parts thereof with removed or damaged nameplate (rating plate) and/or warranty seals.
- 11. The buyer/warranty rights holder is required to operate the equipment properly and carry out technical inspection and maintenance in accordance with the section "MAINTENANCE AND SERVICING" in the following Operating and Maintenance Manual.
- 12. This warranty shall be made immediately void and null if:
  - The buyer/warranty rights holder modifies the product design without prior authorisation from MERCOR
  - Periodic technical inspection and/or maintenance is not carried out per schedule and/or is carried out by unauthorised personnel or service providers not authorised to do so by MERCOR and/or the equipment has not been properly operated.
  - Unauthorised personnel attempts any intervention in the product outside of the normal operation and maintenance of this equipment.
  - The device's thermal trigger was affected by a temperature greater than Tmax (page 3 of the Operation Manual).
- 13. Any circumstances listed in Item 10 will relieve MERCOR from the obligation of surety.

The relevant provisions of the Polish Civil Code shall apply to all matters not regulated in these Warranty Terms & Conditions.

CE	
1396	
MERCOR S.A. and 380-470	
16	
1396-CPR-0114	
PN-EN 15650:2010 (EN 15650:2010)	
Fire damper	
mcr FID S/S c/P	
Nominal activation conditions /	
sensitivity:	Positive result
- sensor activation temperature	Positive result
- reliability sensor	
Response time:	
- closure time	Positive result
Reliability:	10 000 cycles - Positive result
Fire resistance:	
- Integrity E	
- Insulation I	EI 120 (ve $h_0$ i< >0)S
- Smoke leakage S	EI 120 ( $v_e <>0$ )S
- Mechanical stability (E class)	
- Maintenance of the cross section (E class)	
Operation time durability:	
- sensor activation temperature	Positive result
- reliability sensor	
Operational reliability stability:	
- opening / closing cycle test	Positive result